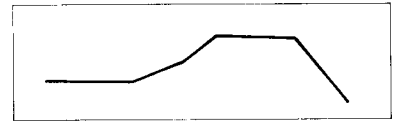
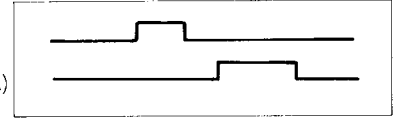


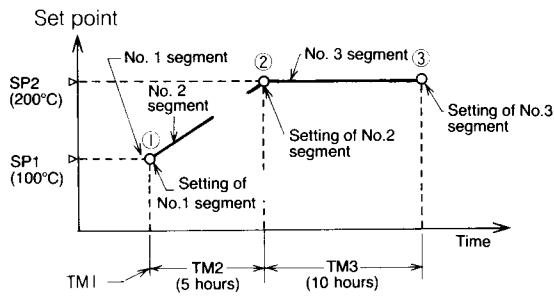
## Program pattern

Map position	Segment item	1	2	3	...	...	20
A	SP						
	Time						

Main function  
(pattern data)Subfunction  
(events and other data)

## How to set a program pattern:

## Set point

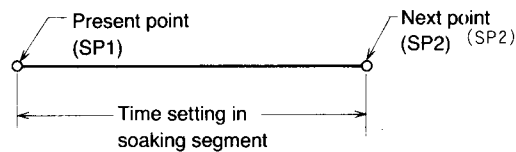


- (1) Set the basic program pattern.
- (2) Prepare each segment (broken line) sequentially by assigning one point as shown in ①, ②, ③ in the left figure.
- (3) Assign points ①, ②, ③ by combining SP (set points) and TM (time) switch each other.
- (4) The unit of TM (time) is either hour/minute or minute/second, and it can be assigned by SET UP C29.

Perform operation according to the assignment of C29 in the operation mode, irrespective of the assignment in the programming mode.

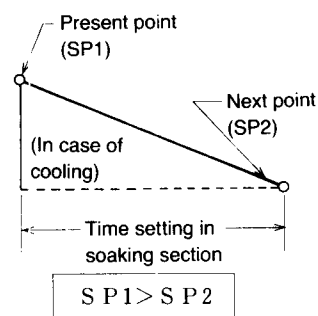
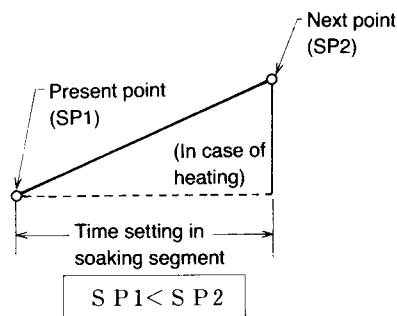
Segment No.	SP (Set point)	TM (time)	Description
1	100°C	0 hour	Start point designation. Soaking for 0 hour at 100°C
2	200°C	5 hours	Ramp segment designation. Heating for 5 hours up to 200°C
3	200°C	10 hours	Soaking segment designation. Soaking for 10 hours at 200°C

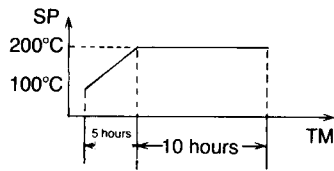
For setting the soaking segment, set the SP (set point) of the present point to the SP of the next point.



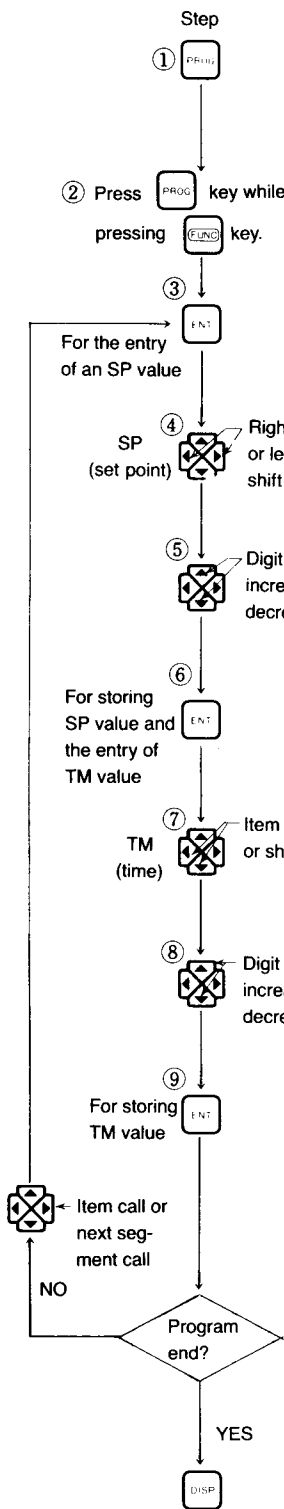
$$SP1 = SP2$$

For setting the ramp, make a differential between the SP (set point) at the present point and the SP at the next point.

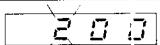
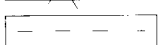


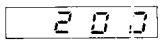
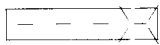


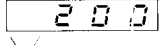
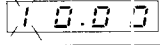


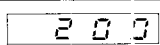
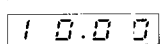


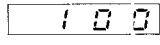
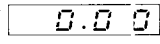








SP	Input range. Limit range when SP limit is set.
TM	0 to 99 hours 59 minutes



Map position	Key operation	Display	Description of display	Display of profile
A 1	Press <b>PROG</b> key.	PROG SEG 	Specifies program No. SP, TM, LED light.	
A 1	Press <b>PROG</b> key while pressing <b>FUNC</b> key.	SP --- TM ---	Sets to programming mode. PRG LED lights. PROG SEG decimal points light.	
A 1	Press <b>ENT</b> key.	SP --- TM ---	Segment 1 The last digit in SP display flashes. SP (set point) entry operation	
A 1	Press this key.	SP --- TM ---	Press this shift key (left), or continue pressing this shift key.	
A 1	Press this key.	SP 0100 TM ---	Increase the flashing digit by a digit increase key. Set SP=100(°C).	
A 1	Press <b>ENT</b> key.	SP 100 TM ---	The last digit in TM display flashes. TM entry operation	
A 1	Press this key.	SP 100 TM 00.00	Under this condition because TM=0 (hour)	
A 1	Press <b>ENT</b> key.	SP 100 TM 0.00	SP=100°C/TM=0 (hour) stored.	
A 2	Press this key.	SP --- TM ---	Segment 2 PROG SEG 1. 2.	
A 2	Press <b>ENT</b> key.	SP --- TM ---	SP entry operation	
A 2	Repeat (4) to (5) steps	SP 0200 TM ---	Set SP=200(°C).	
A 2	Press <b>ENT</b> key.	SP 200 TM ---	The last digit in TM display flashes. TM entry operation	
A 2	Repeat (7) to (8) steps	SP 200 TM 05.00	Set TM=5 (time).	
A 2	Press <b>ENT</b> key.	SP 200 TM 5.00	SP=200(°C)/TM=5 (hours) stored.	
A 3	Press this key.	SP --- TM ---	Segment 3 PROG SEG 1. 3.	
A 3	Press <b>ENT</b> key.	SP --- TM ---	SP entry operation	

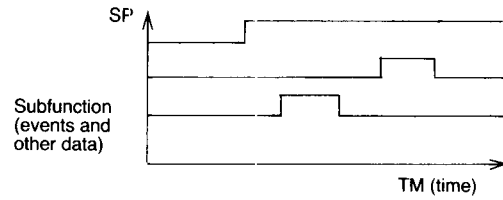
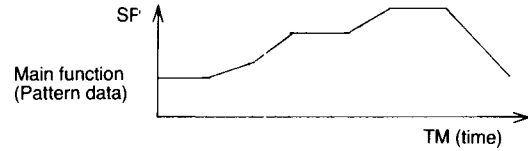
Map position	Key operation	Display	Description of display	Display of profile
A 3	Repeat ④ to ⑤ steps	SP  TM 	Set SP=200(°C).	
A 3	Press  key.	SP  TM 	The first digit in TM display  flashes.	
A 3	Repeat ⑦ to ⑧ steps	SP  TM 	Set TM=10 (hours).	
A 3	Press  key.	SP  TM 	SP=200°C/TM=10 (hours) stored.	
—	Press  key.	SP  TM 	Programming mode ends.	

Press  key during the flashing of SP or TM data. If the  key is pressed while pressing  key instead of setting data, all program data after the segment is deleted. Therefore, if this operation is done at the first segment, the entire program data are deleted.

Complete the program work sheet.

Map position	Segment	1	2	3	...	20
A	S P . T M					
B	E V 1					
C	E V 2					
L	Cycle setting					

Map position	Segment	1	2	3	...	20
B	EV1 event No.1					
C	EV2 event No.2					



Finish the setting of the parameter mode items  $\boxed{9} \boxed{E E 1}$  and  $\boxed{10} \boxed{E E 2}$  first.

1. PV-based event circuit setting:

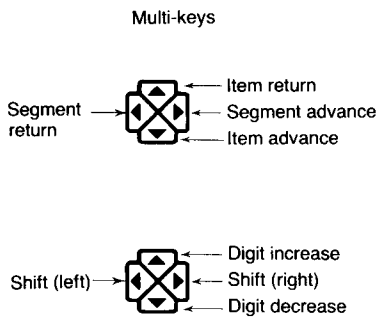
The PV-based event circuit is operated by comparing a PV and an event set point with each other.

Type of event	Relay action
PV (direct) (Off in ready mode)	
PV (reverse) (On in ready mode)	

2. DEV-based event circuit setting:

The DEV-based event circuit is operated by comparing a deviation (PV-SP) and an event set point with each other.

Type of event	Relay action
DEV (direct) (Off in ready mode)	
DEV (reverse) (On in ready mode)	



Setting range	
PV event	Input range
DEV event	0 to 50% FS of input range

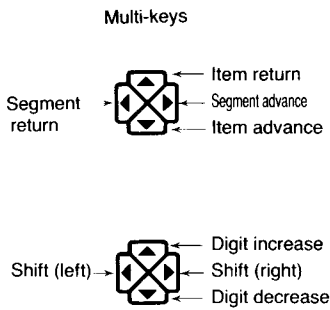
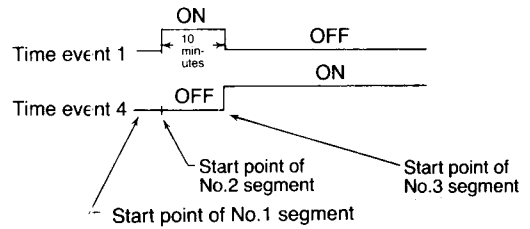
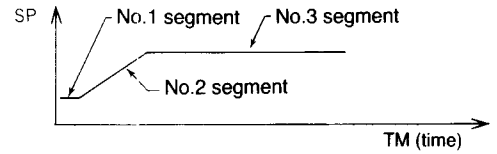
Map position	Keying operation	Display	Description
B 3	<ol style="list-style-type: none"> <li>Press item advance key.</li> <li>Press segment advance key.</li> </ol>		Shift's to B3 position ①PRG, EV1, and PV of display light. ②D splay segment (map B3) for event setting.
B 3	Press $\boxed{ENT}$ key.		The first digit in a lower-display flashes.
B 3	<ol style="list-style-type: none"> <li>Press shift key.</li> <li>Press digit increase key.</li> </ol>		Enter 100(°C).
B 3	Press $\boxed{ENT}$ key.		Store PV event 100°C.

(Note) Setting is deleted by pressing  $\boxed{CLR}$  key while pressing  $\boxed{CLR}$  key instead of  $\boxed{ENT}$  key.

### 3. Time-based event circuit setting:

Map position	Segment	1	2	3	...	20
D	T1 time event					
E	T2 time event					
F	T3 time event					
G	T4 time event					

Time-based event circuit turns on and off with the program time, irrespective of the control output. They are specified by the time from the start point of the set segment.

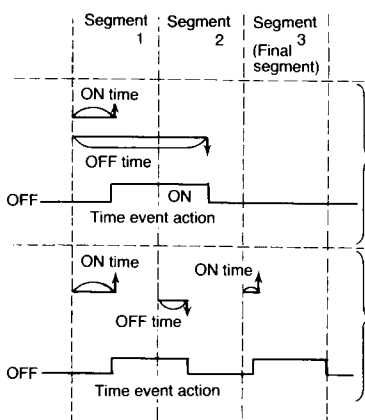


Map position	Key operation	Display	Description
D 2	① Press item advance key. ② Press segment advance key.	SP: [---] TM: [---]	Shift to D2 position ① RPG and T1 light. ② Display segment (map D2) for event setting.
D 2	Press <b>ENT</b> key.	SP: [---] TM: [---]	Press <b>ENT</b> key the first digit in upper display flashes for ON time setting.
D 2	Press <b>1</b> key.	SP: [0.0.0] TM: [---]	Set the time to turn on (0:00 in this case).
D 2	Press <b>ENT</b> key. (Note)	SP: [0.0.0] TM: [---]	Press <b>ENT</b> key the first digit in a lower display flashes for OFF time setting.
D 2	① Press the shift key (left). ② Press the numeric value increase key.	SP: [0.0.0] TM: [1.0.0]	Set the time to turn off (10:00 in this case).
D 2	Press <b>ENT</b> key. (Note)	SP: [0.0.0] TM: [1.0.0]	Time event 1 setting { ON: 0:00 OFF: 10:00

(Note) Setting is cancelled by pressing **CLR** key while pressing **ENT** key instead of pressing **ENT** key.

Setting item	Contents
Upper display	ON time
Lower display	OFF time

Setting range	
ON time	0:00 to 99:59
OFF time	0:00 to 99:59



**Example 1** In example 1, ON time and OFF time are set as one set at segment 1. Time event setting for a time exceeding the time of one segment is also possible.

**Example 2** In example 2, the ON time only is set at segments 1 and 3, while the OFF time only is set at segment 2. ON and OFF can be set without combining ON and OFF time as one set. The time-based event circuit is turned off when the program ends.

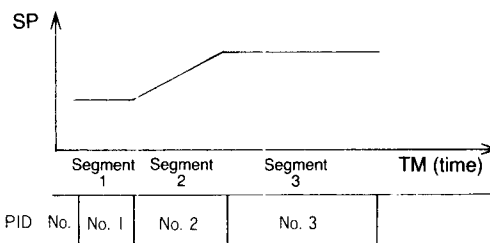
#### 4. PID group selection

Map position	Segment	1	2	3	20
H	PID group selection				

PID group No. to be employed in a segment is specified out of PID1, PID2, and PID3.

Set point	Contents
1	PID 1 group is used.
2	PID 2 group is used.
3	PID 3 group is used.

Multi-keys



Map position	Key operation	Display	Description
H 2	① Press item advance key. ② Press segment advance key.	P i d 1	Shifts to H2 position. ① P i d. 1 is displayed in the upper display. ② Display the segment (map H2) for PID setting.
H 2	Press ENT key.	P i d 0 0 0 1	1 flickers in the lower display.
H 2	① Press digit increase key.	P i d 0 0 0 2	Increase the flashing digit to 2.
H 2	Press ENT key.	P i d 2	Store PID group No.2.

Note: PID values of each group are set by either PID tuning mode or AT action.

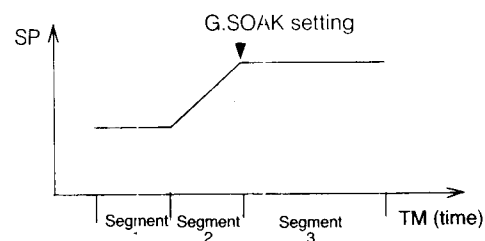
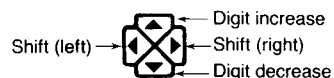
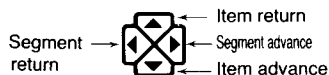
#### 5. G.S (guaranteed soak) setting

Map position	Segment	1	2	3	20
I	G.S setting				

Specify this item for setting G.SOAK (guaranteed soak).

Setting item	Contents
YES	G.SOAK is set.
no	G.SOAK is not set.

Multi-keys



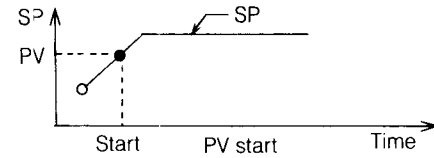
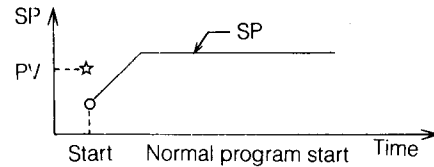
Map position	Key operation	Display	Description
I 3	① Press item advance key. ② Press segment advance key.	9.5. no	Shifts to I3 position. ① LED lights. ② Display the segment (map I3) for G.SOAK setting.
I 3	Press ENT key.	9.5. no	Press ENT key. no flashes.
I 3	① Press item return key.	9.5. YES	YES flashes.
I 3	Press ENT key.	9.5. YES	YES is set.

## 6. PV start setting

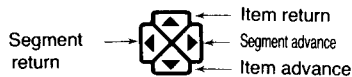
Map position	Segment	1	2	3	20
J	PV start setting				

Specify this item for starting the program from the present PV.

Setting item	Contents
YES	PV start is executed.
NO	PV start is not executed.



Multi-keys (nominal)

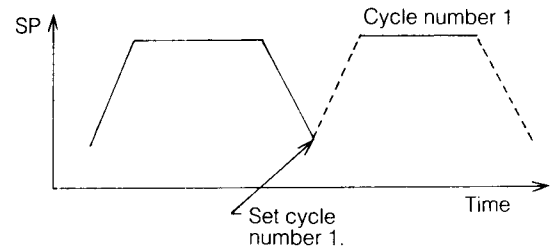


Map position	Keying operation	Display	Contents
J 1	① Press item advance key.	P.S t A n o	Data are displayed in the upper display. (Note) YES or NO of PV start can be set at any optional segment.
J 1	Press  key.	P.S t A n o	NO flashes.
J 1	① Press item return key.	P.S t A Y E S	YES flashes.
J 1	Press  key.	P.S t A Y E S	YES is set.

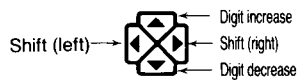
## 7. Cycle setting

Map position	Segment	1	2	3	20
K	Cycle setting				

Specify this item for executing the same program repeatedly.



Multi-keys (nominal)



Map position	Key operation	Display	Description
K 3	① Press item advance key. ② Press segment advance key.	C Y C L 0	Shifts to K3 position. ① CYCL 0 is displayed in the upper display. ② Cycle number can be set in any optional segment.
K 3	Press  key.	C Y C L 0	Press ENT key, 0 flashes.
K 3	① Press the digit increase key.	C Y C L 1	Assume that the cycle number is 1, set the digit to 1. 1 flashes.
K 3	Press  key.	C Y C L 1	Cycle number 1 is set.

## 6.

## PID TUNING

**General**

Specify and set P (proportional band), I (integral time), D (derivative time), and the upper-limit and lower-limit of manipulated variables.

Tuning is done by either manual tuning or auto tuning.

- Manual tuning (PID constants are set manually.)
- Auto tuning (PID constants are automatically set.)

Display/ setting order	Code	Tuning item	Selection or setting range	Initial value in display	Description
1	<i>AT</i>	Auto tuning selection	0: AT is not executed 1: Method 1 is executed by AT key. 2: Method 2 is executed by AT key.	0	Displayed only when auto tuning is provided. (Note) For methods, 1 and 2, see page 37.
2	<i>P - 1</i>	Proportional band 1	0.0 to 999.9% (time propor- tional) type 0.1 to 999.9% (current out- put) type	100.0	
3	<i>I - 1</i>	Integral time 1	0 to 3600 sec	0	Displayed when P≠0.
4	<i>d - 1</i>	Derivative time 1	0 to 1200 sec	0	Displayed when P≠0.
5	<i>oL - 1</i>	MV lower-limit 1	0.0 to upper-limit % (time proportional) type -10.0 to upper-limit % (cur- rent output) type	0.0 -10.0	Displayed when P≠0.
6	<i>oH - 1</i>	MV upper-limit 1	Lower-limit to 100.0% (time proportional) type Lower-limit to 110.0% (current output) type	100.0 110.0	Displayed when P≠0.
7	<i>rE - 1</i>	Manual reset 1	0.0 to 100.0%	50.0	Displayed when P≠0 and I=0.
8	<i>P - 2</i>	Proportional band 2	0.0 to 999.9% (time proportional) type 0.1 to 999.9% (current output) type	100.0	
9	<i>I - 2</i>	Integral time 2	0 to 3600 sec	0	Displayed when P≠0.
10	<i>d - 2</i>	Derivative time 2	0 to 1200 sec	0	Displayed when P≠0.
11	<i>oL - 2</i>	MV lower-limit 2	0.0 to upper-limit % (time proportional) type -10.0 to upper-limit % (cur- rent output) type	0.0 -10.0	Displayed when P≠0.
12	<i>oH - 2</i>	MV upper-limit 2	Lower-limit to 100.0% (time proportional) type Lower-limit to 110.0% (cur- rent output) type	100.0 110.0	Displayed when P≠0.
13	<i>rE - 2</i>	Manual reset 2	0.0 to 100.0%	50.0	Displayed when P≠0 and I=0.
14	<i>P - 3</i>	Proportional band 3	0.0 to 999.9% (time propor- tional) type 0.1 to 999.9% (current out- put) type	100.0	
15	<i>I - 3</i>	Integral time 3	0 to 3600 sec	0	Displayed when P≠0.
16	<i>d - 3</i>	Derivative time 3	0 to 1200 sec	0	Displayed when P≠0.
17	<i>oL - 3</i>	MV lower-limit 3	0.0 to upper-limit % (time proportional) type -10.0 to upper-limit % (cur- rent output) type	0.0 -10.0	Displayed when P≠0.
18	<i>oH - 3</i>	MV upper-limit 3	Lower-limit to 100.0% (time proportional) type Lower-limit to 110.0% (cur- rent output) type	100.0 110.0	Displayed when P≠0.
19	<i>rE - 3</i>	Manual reset 3	0.0 to 100.0%	50.0	Displayed when P≠0 and I=0.
20	<i>I o u t</i>	PID operation Initial MV	0.0 to 100.0%	0.0	Displayed, if at least one P=0 out of 1 to 3 groups.



# PID tuning procedure

Refer to the key operation note on page 15.

For the contents of PID tuning mode, see page 36.

This paragraph describes the operating procedures for the selected PID tuning items out of No. 1 to 20.

Press PID key.

## 1 Auto tuning selection

SP A t  
 TM 1

Initial tuning display:  
 0: AT is not executed.  
 1: Method 1 is executed by AT key.  
 2: Method 2 is executed by AT key.

Auto tuning method 1 or 2 is described below.

### 1: Method 1

The most popular control constants can be set automatically. Overshoot may more or less occur. This method is used when the arrival time to a set point is regarded as important.

### 2: Method 2

This method is used when noticeable overshoot is presumable on an equipment or when it is desired to suppress overshoot. In many cases, the overshoot is restricted. However, rising is apt to be delayed.

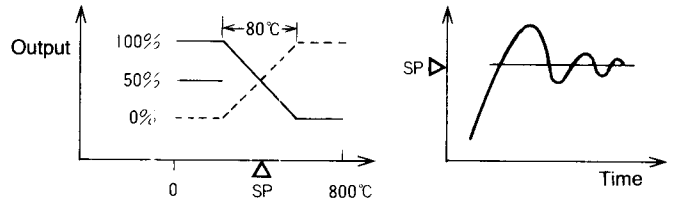
I and D: Unlike in on/off action, the P control action does not easily produce any undulation phenomenon. However, it is possible that the temperature remains deviated from a set point.

I and D control action are provided for preventing such a failure. In electric furnaces, I is generally set to 150 sec, while D is generally set to about 30 sec. As I becomes shorter, or as D becomes longer, the control function becomes stronger. However, the control function is too strong to ensure the control to be executed satisfactorily at all times. Both I and D are off at 0.

(Examples)

In case of 10% proportional band in 0° to 800°C range, P is 80°C.

If I is short (strong), the control may often become excessive.



## 2 Proportional band 1

SP P - 1  
 TM 1 0 0 . 0

Initial tuning display

## 3 Integral time 1

SP I - 1  
 TM 0

Initial tuning display

## 4 Derivative time 2

SP d - 1  
 TM 0

Initial tuning display

Setting range:  
 $P-1, P-2, P-3$  :  $\begin{cases} 0.0 \text{ to } 999.9\% \text{ (time proportional type)} \\ 0.1 \text{ to } 999.9\% \text{ (current output type)} \end{cases}$   
 $I-1, I-2, I-3$  : 0 to 3600 sec  
 $d-1, d-2, d-3$  : 0 to 1200 sec

P: This constant determines the deviation ratio of a PV to a set point of a temperature, where the control output is to be set to 0 or 100. This value is set by %, and an about 10% is generally used for electric furnaces.

As this range becomes narrower, the sensitivity becomes higher. But, if the range is extremely narrow, an undulation phenomenon occurs.

## 5 MV lower-limit 1

SP o L - 1  
 TM 0 . 0

Initial tuning display

## 6 MV upper-limit 1

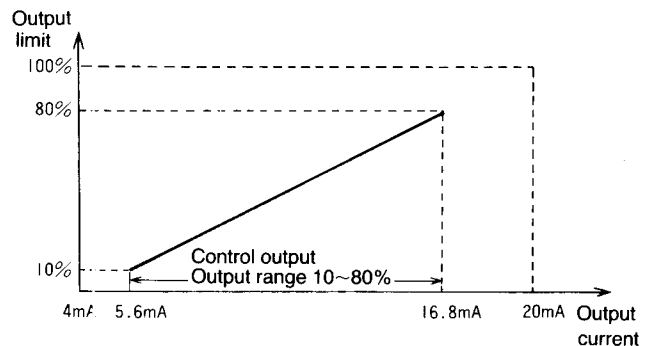
SP o H - 1  
 TM 1 0 0 . 0

Initial tuning display

Setting range

$oL-1, oL-2, oL-3$  : 0.0 to upper-limit %  
 (Time proportional type)  
 -10.0 to upper-limit %  
 (Current output type)








$oH-1, oH-2, oH-3$  : Lower-limit to 100.0%  
 (Time proportional type)  
 Lower-limit to 110.0%  
 (Current output type)



Check and set the following items before starting the program.

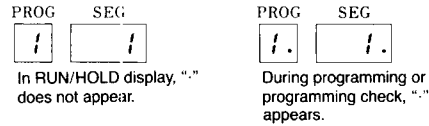
1. Is PV start executed?  
See page 19, 35.
2. Is auto tuning executed?  
See page 36, 37.
3. Are PID constants set? Is the output limiter set?  
See page 34, 36.
4. Is PV bias used?  
See page 24, 25.
5. Is SP bias used?  
See page 24.
6. Is PV filter used?  
See page 24, 25.
7. Is the MV change quantity limit set?  
See page 24, 26.
8. Is the program protect function provided?  
See page 24, 25.


### Key operation

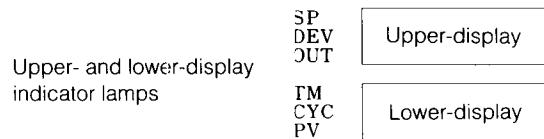
-  : Specifies the program number.
-  : Change the mode from ready to RUN or from RUN to HOLD.
-  : Specifies the display contents of the upper-display and lower-display.
- \* For resetting to the ready mode (from RUN or HOLD), press  key while pressing  key.
- \* For advancing the segment by one under RUN/HOLD mode, press  key while pressing  key.

### Monitoring during program run

1. The program number and segment number display contents are as shown below during run and programming check.



2. When  key is pressed, the upper- and lower-display indicator lamps indicate the contents of both upper- and lower-display by their combinations. The upper- and lower-display indication lamps are combined with each other as follows.



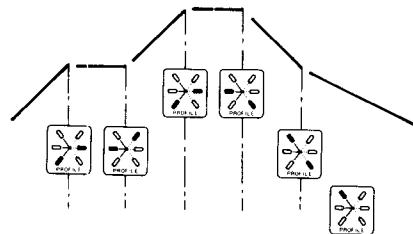
Combinations of upper- and lower-display indicator lamps

Upper-display	SP	DEV	OUT	TM	CYC	SP
Lower-display	PV	PV	PV	PV	PV	TM


3. Mode indication by mode indicator LED lamps

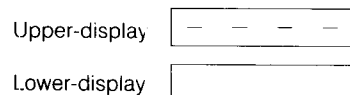
RUN: Lights during run.  
HLD: Lights during hold.  
MAN: Lights in manual operation mode.  
PRG: Lights in programming mode.  
(Note) None of mode indicator lamps lights under the ready mode.

4. Running pattern conditions, easily monitorable by profile indicator LED lamps



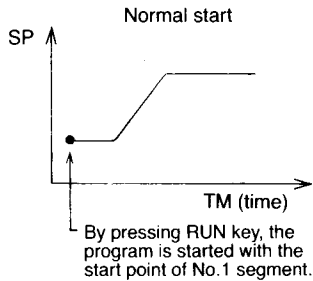
Program status display:

- Indicates rising, soaking, and falling tendencies of program pattern.
  - Indicates the present segment and next segment.
5. For identifying pattern which has already set or not, check if the upper-display shows the following contents when a program number is entered by  key.



# OPERATION EXAMPLES

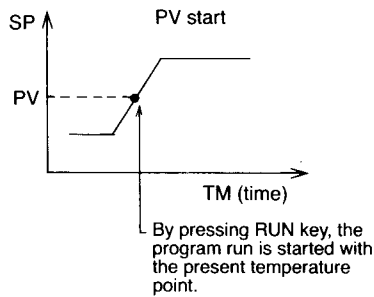
## 1 Starting program



Specify the PV start  $\text{no}$  in programming. See page 35.  
 When PV start is set to  $\text{no}$  in programming, the normal start is done.  
 When PV start is set to  $\text{YES}$  in programming, the PV start is done.

Display	Key operation	Description of contents
	Press  key.	Specify a program No. Press this key by necessary times.
	Press  key.	Runs. •RUN LED lights. •PROFILE LED lights.

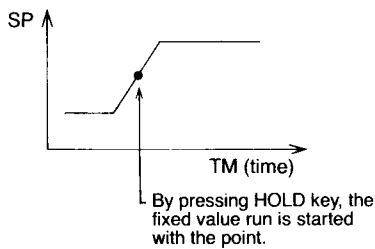
## 2 Starting a program from a preset temperature



Specify PV start  $\text{YES}$  in programming. See page 35.

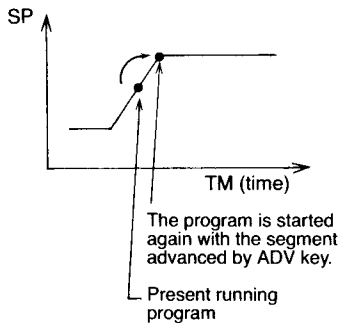
Display	Key operation	Description of contents
	Press  key.	Specify a program No. Press this key by necessary times.
	Press  key.	Runs. •RUN LED lights.

## 3 Holding a program



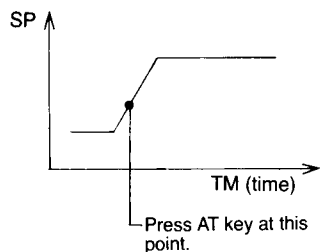
Display	Key operation	Description of contents
	Press  key.	Holds. •HOLD LED lights.

## 4 Advancing a program to a new segment



Display	Key operation	Description of contents
		Running.
	Press  key while pressing  key.	Perform ADV operation. The program proceeds to the start point of the next segment.

## 5 Starting auto tuning



Display	Key operation	Description of contents
		During RUN or HOLD.
	Press  key.	Auto tuning is started. •AT LED lights.
		Auto tuning ends automatically.

### Description of auto tuning (AT) (option)

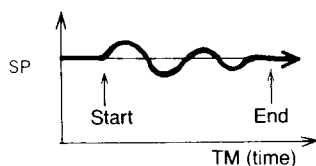
• Auto tuning is executed only when all the following conditions are satisfied.

- ① RUN or HOLD mode
- ② AUTO mode
- ③ PID constant is set to "1" or "2".
- ④ PV is within the range.

• When auto tuning ends, the PID group constants used for the segment are replaced with new constants by auto tuning.

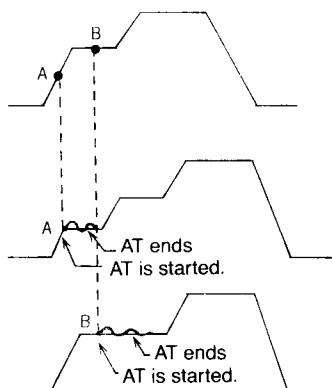
• For stopping this auto tuning, press key during auto tuning. The auto tuning stops, and PID constants are not rewritten.

### Auto tuning method:



The on-off operation is repeated twice at about the set point of a temperature, and PID values newly calculated are used.

Whether the first control action is on or off depends upon the condition of PV and SP at that time.



#### Auto tuning at point A

Be careful because a stepwise pattern appears halfway in the course of ramp.

#### Auto tuning at point B

The program automatically stops advancing temporarily when executing auto tuning. It is automatically restarted after the end of auto tuning.

## 6 Selecting manual control for the process

Display	Key operation	Description of contents
	Press  key.	Upper-display for main output (MV or SP). Lower-display for PV.
	Press  key.	MV or SP change Set an output value by multi-keys. The value is effective, even if  key is not pressed.

Press key when returning to the automatic operation mode.

### 7 Stopping a program

Display	Key operation	Description of contents
		Running
	Press  key while pressing  key.	Program is reset to the ready mode. •RUN and HLD LEDs are off.

### 8 Copying stored program data under a different program number

Display	Key operation	Description of contents
	Press  key.	Select a program number of the copy source by PROG key in an AUTO mode.
	Press  key while pressing this key.	<b>COPY</b> is indicated on the upper-display, and ---- is indicated on the lower-display. No display appears, if the copy source is not available.
	Press this key.	Select a program number in the lower-display program number is not displayed if some program is set already for the number.
	Press  key.	Press ENT key to copy the program. However, it is not copied, if the total number of preset events of the instrument exceeds 200, the lower-display indicates ----.
	Press  key.	Returns to the ready mode.

### 9 Changing program data

Select the mode to be corrected.





- Setup mode ———
- Parameter mode: ———
- PID tuning mode: ———
- Programming mode ——— +



Select an item to be corrected by keys, and press key.

Change program data by keys, and press key.

## 10 Storing the setting range limits of a program





$C10$  : Lower-limit value  
 $C11$  : Upper-limit value


Setup mode.   
 Select  $C10$  or  $C11$  by  or  keys, and press  key.



Change the program data by  keys, and press  key.


## 11 Deleting stored data


Set the ready mode.



 +  in RUN/HOLD mode.  
 in MANUAL mode.  
 in other cases.

Select the program No. of the program to be deleted by  key.

Select the programming mode by pressing  key while pressing  key.

Display the values of SP (set point) and TM (time) of segment 1 by  keys.

Start changing the values of SP or TM by  key to flash the value.

The program can be deleted by pressing  key while pressing  key.

## 12 Alarm code display

If a PV alarm or an instrument alarm is detected, a program segment No and its alarm code are displayed on the PROG/SEG indicator alternately every second, but the instrument run and other action are continued. However, if A90 alarm occurs, its alarm code only is continuously displayed on the PROG/SEG indicator, and the lower-stage indicator displays the present board input/output and option type. The instrument does not start any action.

Alarm code	Meanings	Remedial measures
$R 01$	PV is not within a range of $-10$ to $+110\%$ FS	Check the sensor/disconnection.
$R 90$	PC board is not properly mounted. (Check it only when power is turned on.)	Ask for repair.
$R 92$	EEPROM is defective.	Ask for repair.
$R 94$	SETUP and PARA parameter contents were broken.	Reset.
$R 95$	PID parameter contents were broken.	
$R 96$	Program pattern contents were broken.	
$R 98$	RAM is defective.	Ask for repair.
$R 99$	ROM is defective.	

## 13 Condition (of the DCP200) after recovery from a power failure

- A power failure to the DCP200 will occur when its power supply drops below 70V AC and remains below this level for longer than 100 msec.
- After sufficient power has been generated, all functions of the instrument will return to conditions existing before the failure, i.e. the display mode will continue operations from the point immediately before the failure. Operating time will also progress from the point immediately before the failure.  
 However, the LED display and the EVENT operation will only reappear two to three seconds after sufficient power has been generated; upon reactivation, their timing will not coincide with the other operations' timing.

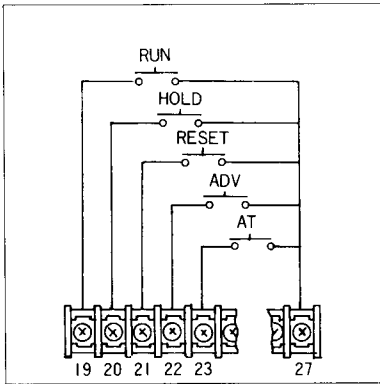
# 8.

# REMOTE OPERATION

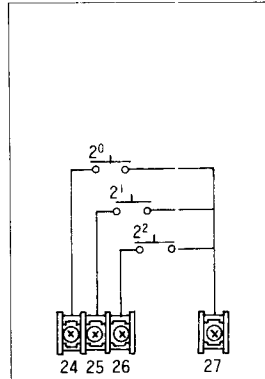
## 1. Remote operation

RUN, HOLD, RESET, ADV, AT, and other operations can be done by using external contacts. An automatic operation of the DCP200 can be made automatically by combining this remote operation function with a sequencer.

### Remote operation terminals



### Program No. selection terminals



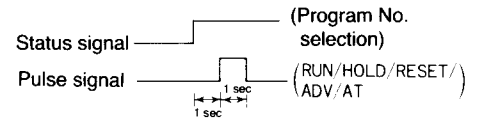
Program No.	Terminal connection
1	②7-②4
2	②7-②5
3	②7-②4, ②7-②5
4	②7-②6
5	②7-②4, ②7-②6
6	②7-②5, ②7-②6
7	②7-②4, ②7-②5, ②7-②6

### (Example) Starting program No. 1

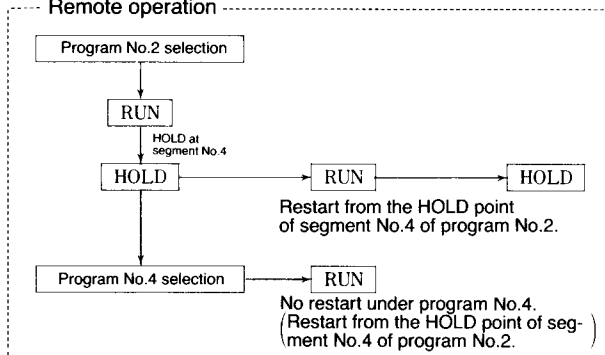
#### Operation

1. Program No. 1 selection ————— ②7 and ②4
2. Program start ————— ②7 and ②5

#### Terminal connection



#### Remote operation



- The remote run start sequence is as follows:  
Turn off RUN, HOLD, RESET, ADV and AT switches, and set three program No. setting switches. After one second or longer, continue turning on the RUN switch for longer than 1 second.

## 2. Description of remote operation

The remote input is acceptable when any one of RUN, HOLD, RESET, ADV and AT switches is turned on continuously for longer than 1 second after three switches of program No. were continued to be held for longer than 1 second with RUN, HOLD, RESET, ADV, and AT switches turned off. Setting of SETUP key lock does not affect any remote operation.

### 1) Remote operation

If a program specified by three program No. switches is already programmed when none of setting operations (programming, PID, PARA, SETUP) is done in the ready mode, the program is started running.

The program runs continuously from the HOLD point in the HOLD mode, irrespective of whether setting operations are executed or not. (The program number of the program to be run remains unchanged even if the specified program number differs from the running program number.)

### 2) Remote HOLD operation

The program is set to HOLD mode during run, irrespective of whether setting operation is done or not.

### 3) Remote RESET operation

The program is set to READY mode (waiting for run) in RUN or HOLD mode, irrespective of whether setting operation is done or not.

### 4) Remote ADV operation

The program advances to the start point of the next segment in RUN or HOLD mode, irrespective of whether setting operation is done or not.

### 5) Remote AT operation (AT function is option.)

Auto tuning is started, if AT is not being executed. Or it is stopped, if AT is being executed when setting operation is not done in RUN or HOLD mode.

### 6) Remote program number selection

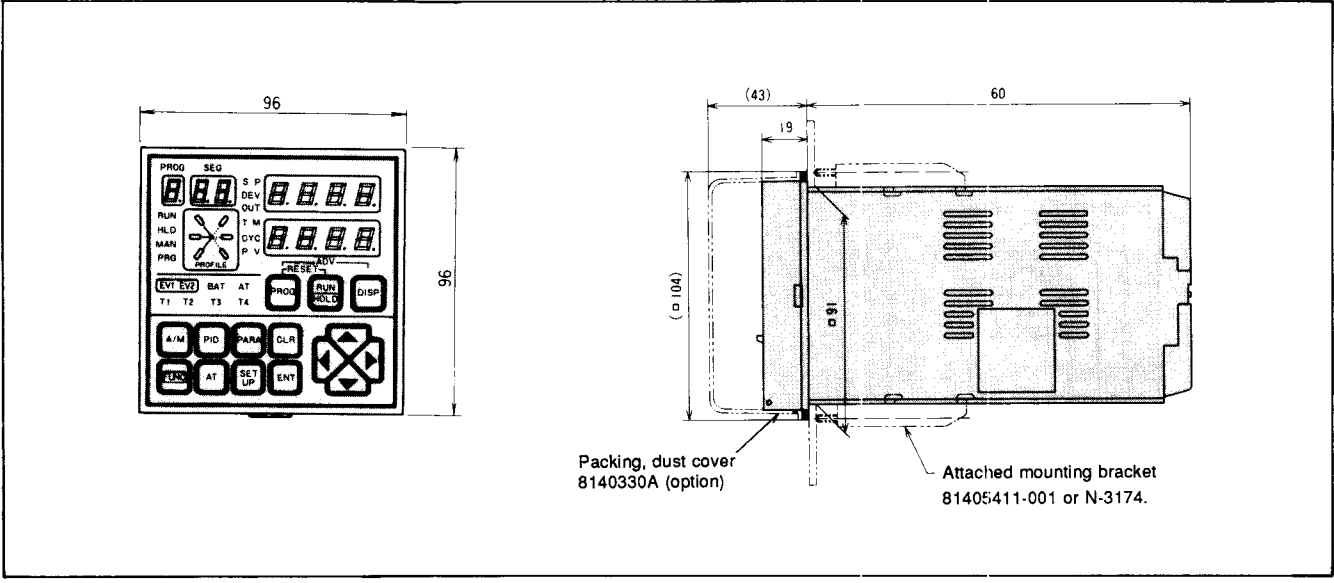
Select a program number (No.1 to 7) by three switches when the remote RUN operation is done in the READY mode. Program No. 0 means the designation of a program which has already been selected by the console.

# 9.

# EXTERNAL DIMENSIONS

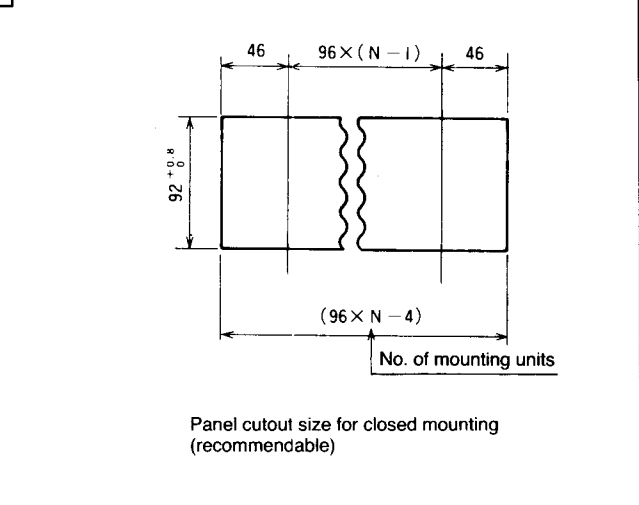
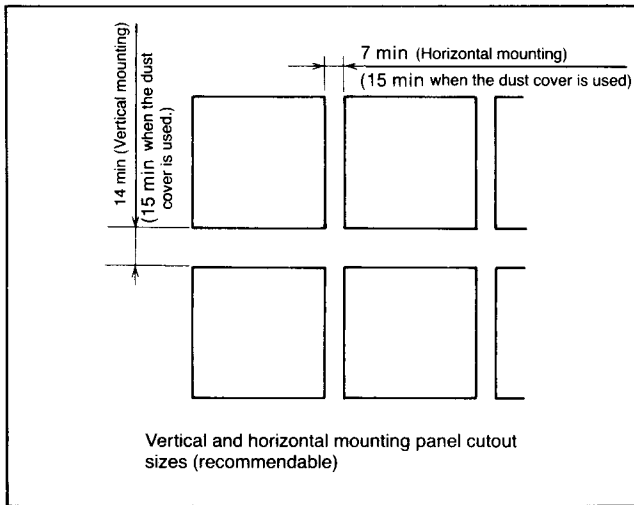
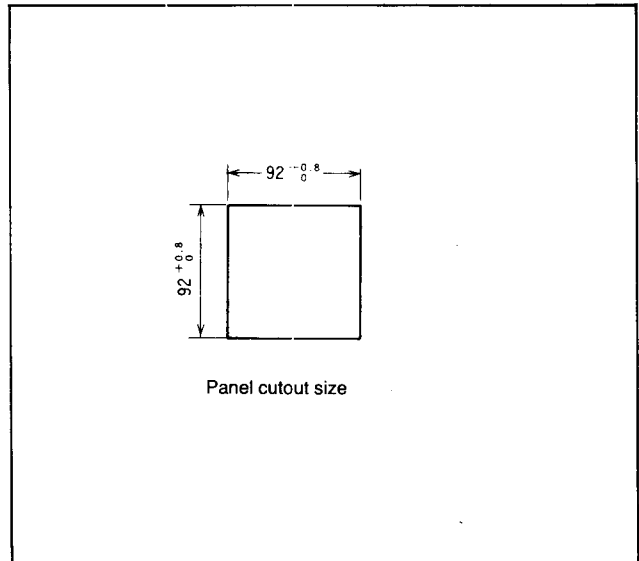
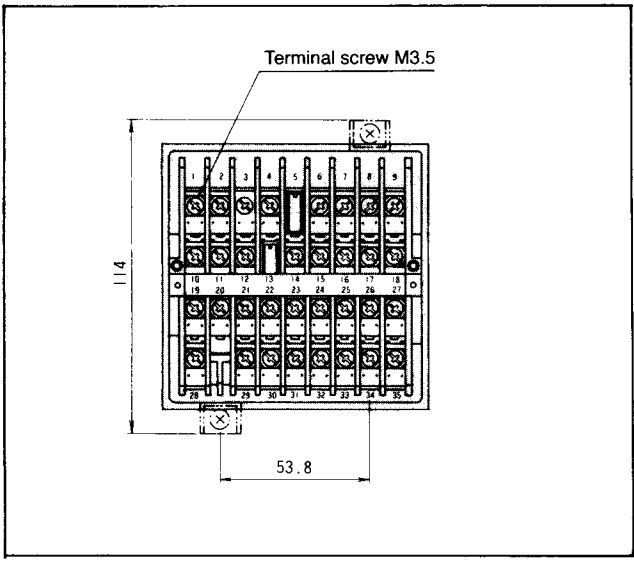
## External dimensions

[in mm]



## Panel cutout size

[in mm]





**1. Mounting place**

Mount the instrument at following places in the same way as in general digital electronic instruments.

- (1) A place free of any noticeable temperature change at normal temperature or so (within 0° to 50°C)
- (2) A place free of a corrosive gas atmosphere
- (3) A place not subjected to a low or high humidity (10 to 90% RH)
- (4) A place free of mechanical vibrations (less than 2 m/s<sup>2</sup>, 10 to 60 Hz)
- (5) A place free of dust particles, soot, or the like
- (6) A place where is not affected by electrical noises
- (7) A place where is not subjected to a strong magnetic field
- (8) A place free of any flammable liquids or vapors.

**2. Mounting method**

- (1) Keep instrument within a mounting angle of 15°, if it is tilted down from the horizontal level on the rear side
- (2) Use a steel panel having a plate thickness of thicker than 2 mm.
- (3) Insert the instrument case from the panel cutout.
- (4) Fix the upper and lower panels of the instrument securely by using the attached mounting brackets.
- (5) Fix the panels to lower mounting bracket (1) first.
- (6) When the mounting brackets are flush against both a and b (where there is no longer any play between the mounting brackets and mounting panel), tighten the screw by about one turn. Do not tighten the screws too hard. Doing so might deform the case.

The controller must be mounted on a mounting panel, and its terminals covered to prevent electrical shock.

An optional terminal cover (Part No.: 81446084-002) is so separately.

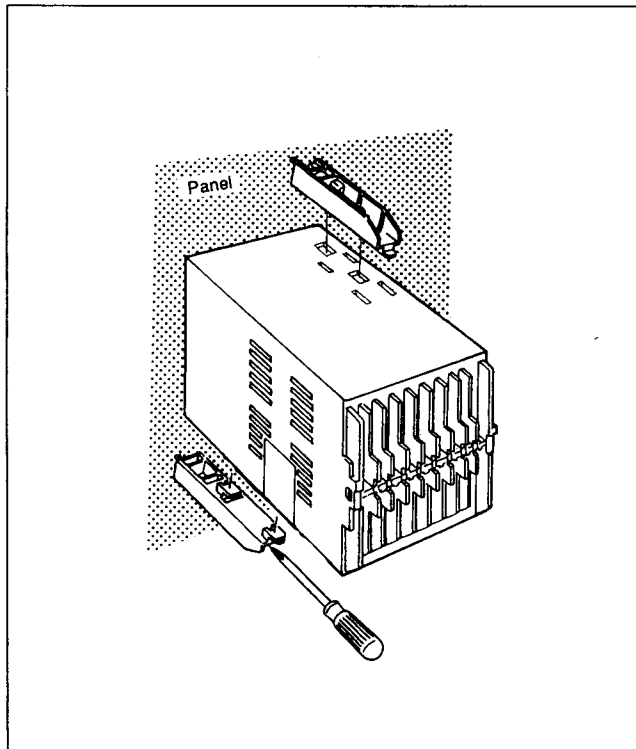


Fig. 10-1 Mounting method

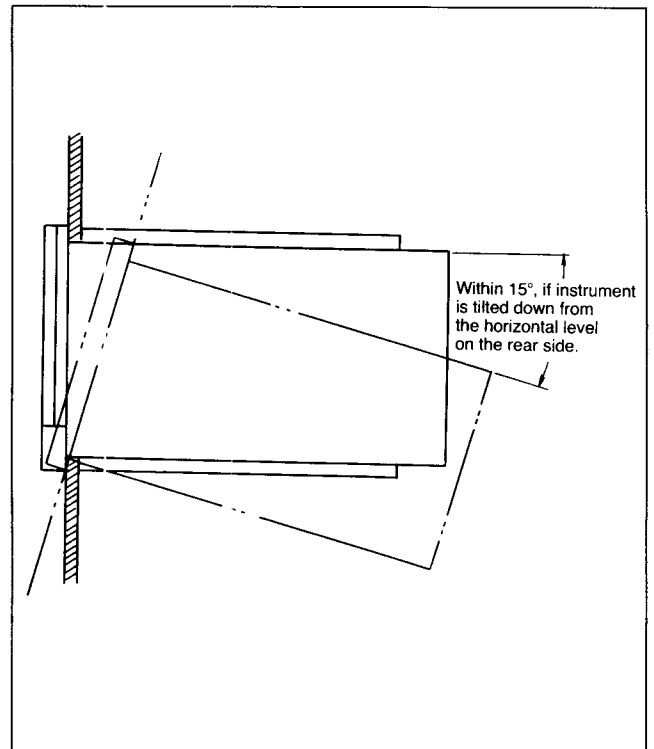


Fig. 10-2 Mounting angle

**Caution:** Use shielded cables for the DCP200 input/output cables so as not to introduce noises.

### 1. Cautions on wiring

- (1) Digital units are apt to be affected by electrical noises, so that a trouble and a wrong operation may be caused by those which are negligible for analog units. In order to prevent an effect of noises, connect cables with due care according to the instructions of this chapter.
- (2) Use solderless terminals conforming to M3.5 screws.
- (3) Connect cables according to the wiring diagram of the corresponding model number after confirming the instrument model number. After wiring, check them for normal conditions.
- (4) Separate input/output signal cables from a power cable as far as possible.  
Don't pass both cables through the same conduit or duct.

## 2. Input/output signal cables

### 2.1 Thermocouple input signal cable

- (1) Connect a thermocouple line cable to terminals in case of a thermocouple input. Connect the thermocouple input by extending it with a compensating lead wire, if the wiring distance is long or a sensor is connected to terminals.  
Use a shielded compensating lead wire.

### 2.2 Input signal cables for those other than thermocouples, and digital input/output signal cables

- (1) Use a shielded polyethylene insulated vinyl sheathed cable for instrumentation use conforming to JCS-364 or equivalent (generally called a twisted shielded for instrumentation use).
- (2) A shielded multiconductor microphone cord (MVVS) may be used, if electromagnetic induction noises are comparatively low.

**References** Recommendable commercially available twisted shielded cables (JAPAN)

Fujikura Cable Co.	2 con- ductors	IPEV-S-0.9 mm <sup>2</sup> ×1 P
	3 con- ductors	ITEV-S-0.9 mm <sup>2</sup> ×1 T
Hitachi Cable Co.	2 con- ductors	KPEV-S-0.9 mm <sup>2</sup> ×1 P
	3 con- ductors	KTEV-S-0.9 mm <sup>2</sup> ×1 T

### 2.3 Remote switch input contact

- (1) Use a no-voltage remote switch input and a micro-current contact.
- (2) Hold a contact signal for longer than one second.

### 2.4 Signal cables for communication use (additional function)

- (1) Be careful since the communication circuit may be broken, if (+) and (--) communication terminals are shorted with each other.
- (2) Don't connect the DCP200 together with another instrument connected to the same RS-422 communication line to the same addresses.  
(Zero has no communication)

## 3. Grounding

- (1) Connect the instrument by one-point grounding to G terminal. Don't perform any jumper wiring. Mount a grounding terminal board (earth bar) separately and connect shielded cables, etc. to ground as shown in Fig. 11-1, since only one G terminal is provided.
  - Grounding type: Category 3 grounding or higher (Lower than 100Ω)
  - Grounding wire: Annealed copper wire of more than 2mm<sup>2</sup> (AWG14)
  - Grounding wire length: Max. 20 m

## 4. Instrument power supply

- (1) Obtain the DCP200 power supply from a single-phase instrument power source in such a way as the instrument is not affected by noises as much as possible.

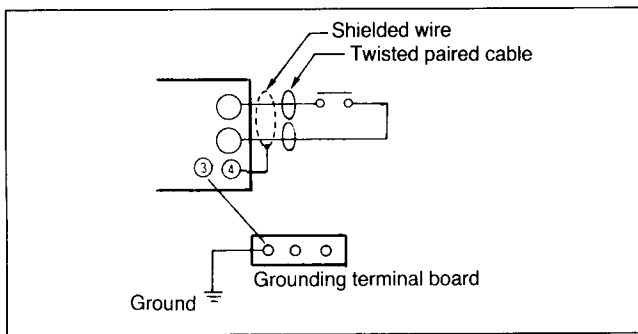


Fig. 11-1 Grounding method

(2) It is recommended to use a line filter having an additional insulation transformer, if noises are introduced noticeably from the power source.

- Line filter  
Part number 81446364-001

Be careful not to bundle the primary and secondary of the power cable together or not to put them into the same conduit or duct after taking a countermeasure against noises.

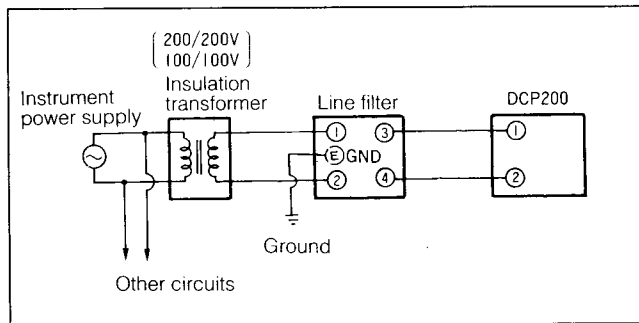


Fig. 11-2 Power noise reduction method

## 5. Noise generation sources and noise reduction methods

### 5.1 Noise generation sources

(1) The following noise generation sources are generally presumable.

- ① Relays and contacts
- ② Solenoid coils and solenoid valves
- ③ Power line (higher than 100 V ac, in particular)
- ④ Inductive load
- ⑤ Motor commutator
- ⑥ Phase angle control SCR
- ⑦ Radio communication equipment
- ⑧ Welding machine

### 5.2 Noise reduction method

(1) A CR filter is effective for quick-rising noises.

- Recommendable CR filter  
Part number 81446365-001  
(XEB120033 manufactured by Matsuo electric or equivalent)

(2) A varistor is effective for noises having a high crest value. Be careful since the varistor is shorted, if it becomes defective.

- Recommendable varistor  
Part number 81446366-001 for 100 V use  
81446367-001 for 200 V use.

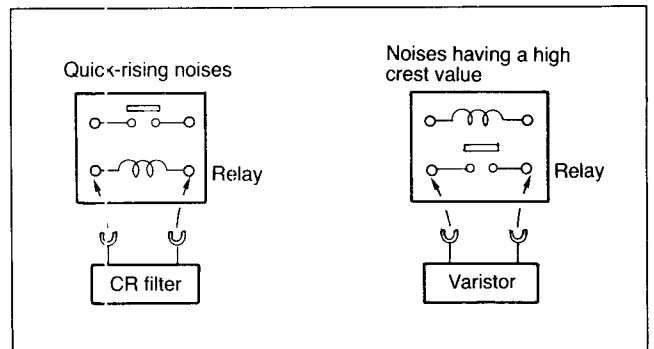
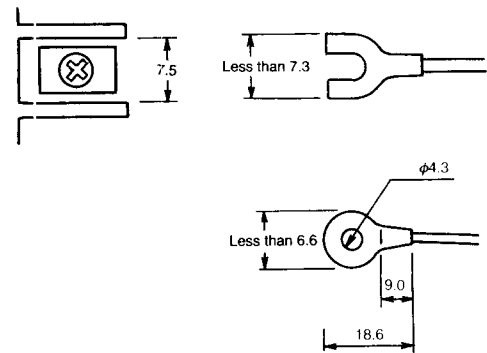


Fig. 11-3 Noise reduction method

For terminal connection, use solderless terminals conforming to M3.5 screws.



(Note) Use circular solderless terminals so that cables are not disconnected from terminals, if the instrument is mounted at a place subjected to noticeable vibrations and impacts.

External terminal layout

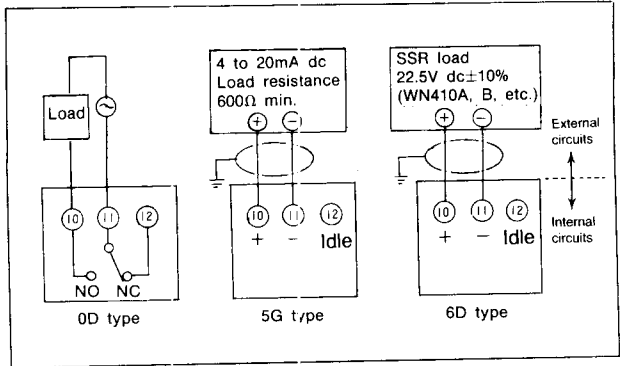
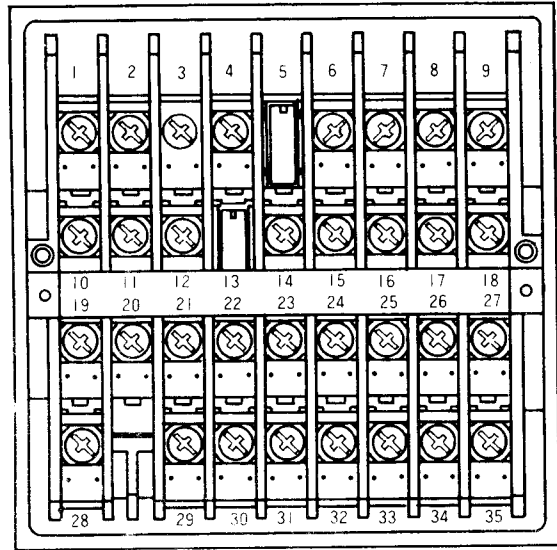
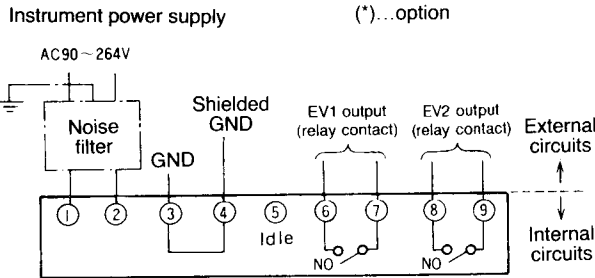


Fig. 12-1 MV output

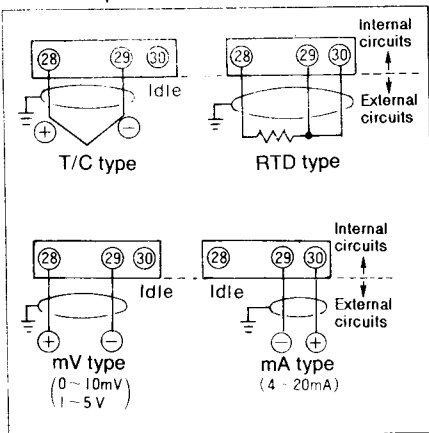
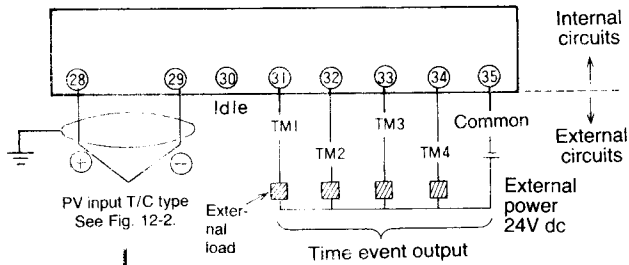


Fig. 12-2 PV input

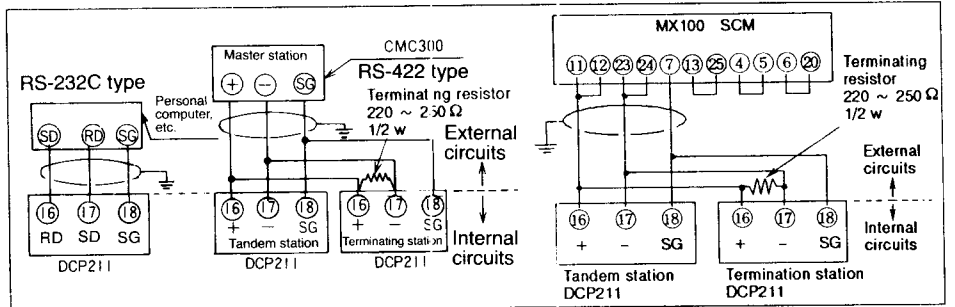
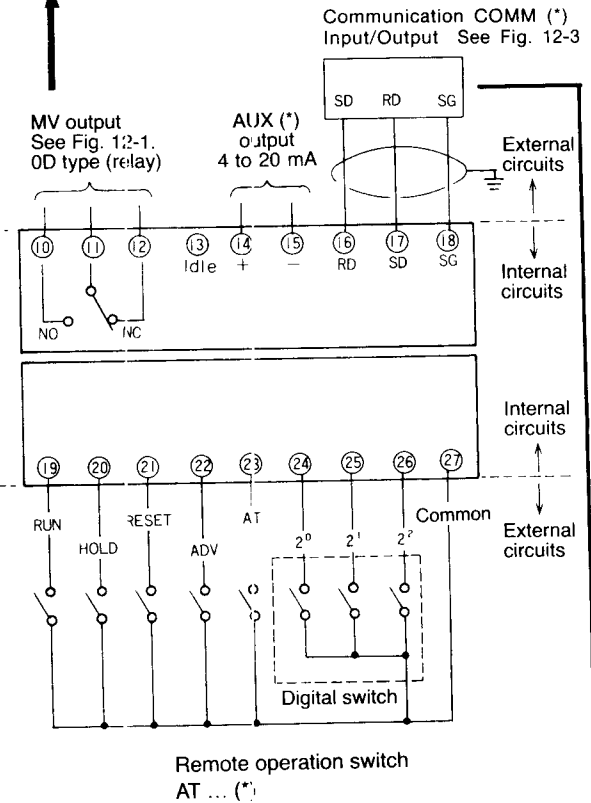






Fig. 12-3 COMM input/output (\*)

- A switch in the main supply is required near the equipment.
- Mains power supply wiring requires a (T) 2A, 250V fuse(s). (IEC127)

The following table shows the meanings of symbols in the terminal wiring label on the instrument top.

Symbol	Description
	Alternating current
	Earth (ground) terminal
	Caution, risk of electric shock
	Caution (refer to accompanying documents)

# 13.

# MAINTENANCE

**Cleaning:** Clean the instrument with a soft, dry cloth when it becomes dirty.

**Replacing Parts:** Only authorized personnel are allowed to replace parts.

**Replacing Fuses:** When replacing fuses provided on the power supply circuit, use only standard parts specified below.

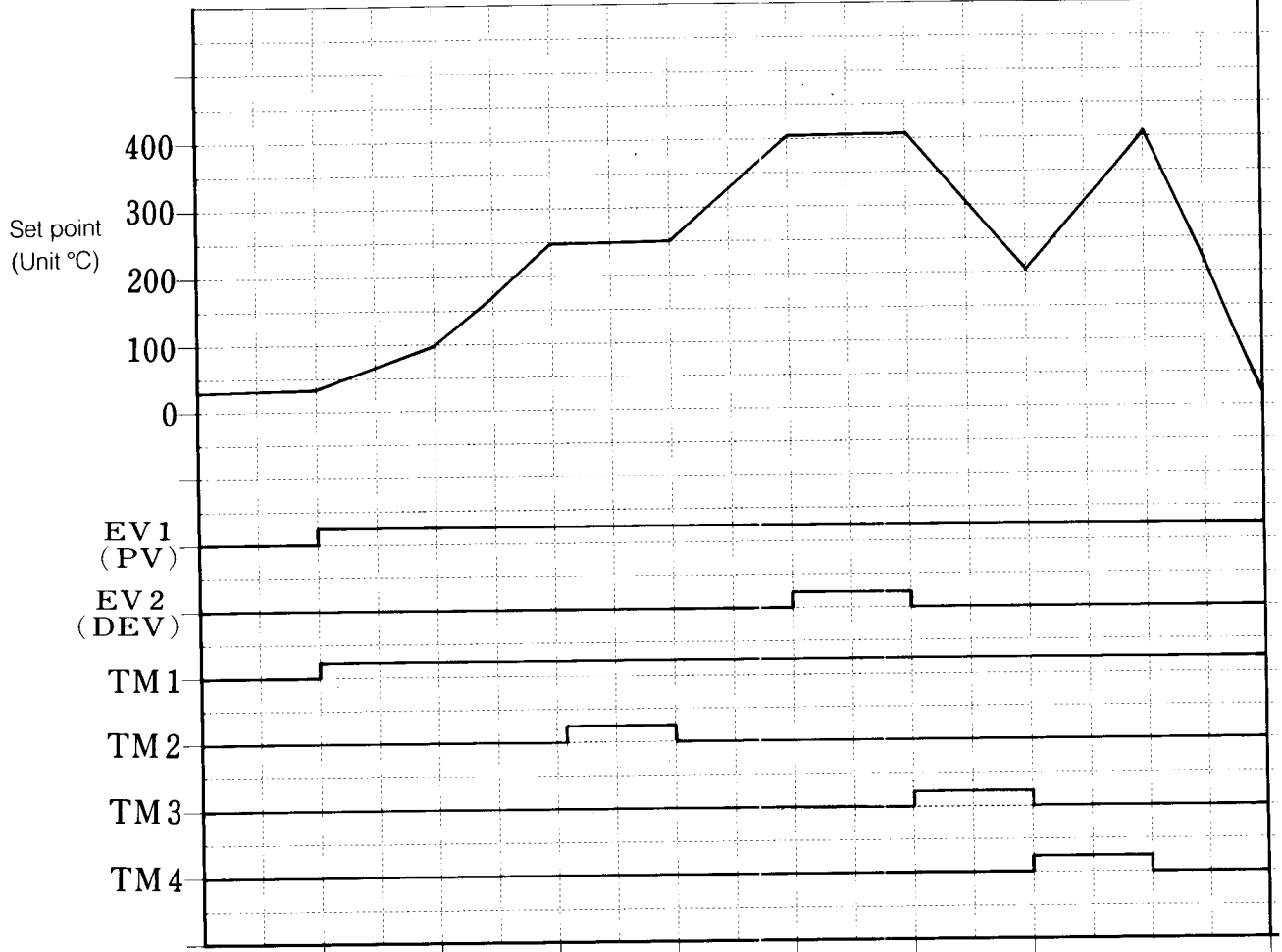
Standard	IEC 127
Type	Time-lag (T)
Voltage rating	250 V
Current rating	2 A

**APPENDIXES**

- (1) Program pattern preparation example**
- (2) Setup setting example**
- (3) Parameter setting example**
- (4) Programming example**
- (5) Program work sheet**

(1) Program preparation example

Program No.:



Programming map

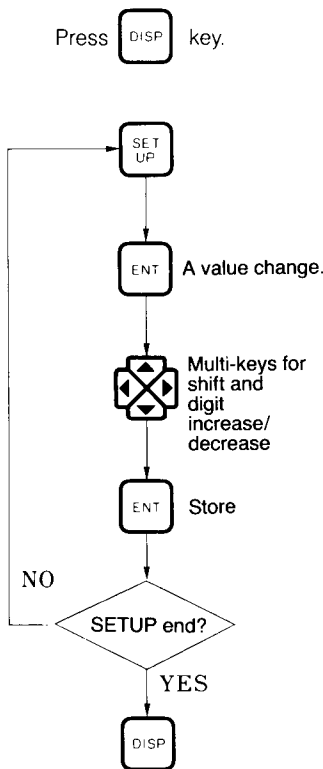
Map position	Segment item	1	2	3	4	5	6	7	8	9			
A	SP time	Upper-display	SP	30	100	250	250	400	400	200	400	30	
		Lower-display	Time	2.00	4.00	3.00	7.00	4.00	7.00	4.00	4.00	4.00	
B	Event No.1	Upper-display	—										
		Lower-display	Set point	(PV) 100									
C	Event No.2	Upper-display	—										
		Lower-display	Set point	(DEV) 5 (DEV) 800									
D	Time event No.1	Upper-display	ON	0.00									
		Lower-display	OFF	37.00									
E	Time event No.2	Upper-display	ON		1.00								
		Lower-display	OFF		7.00								
F	Time event No.3	Upper-display	ON					0.00					
		Lower-display	OFF					7.00					
G	Time event No.4	Upper-display	ON						0.00				
		Lower-display	OFF						4.00				
H	PID group selection	Upper-display	PID										
		Lower-display	Group No.	1	1	1	1	2	2	2	3	3	
I	G.SOAK setting	Upper-display	9.5										
		Lower-display	no or YES	no	no	no	YES	no	no	no	no	no	
J	PV start setting	Upper-display	PStP										
		Lower-display	no or YES	YES	YES	YES	YES	YES	YES	YES	YES	YES	
K	Cycle setting	Upper-display	CYCL										
		Lower-display	Cycle No.	0	0	0	0	0	0	0	0	0	

(Note) Set the max value of segment 7 DEV so as not to allow EV2 to function between segments 7 to 9. -50% FS to +50% FS



## (2) Setup setting example

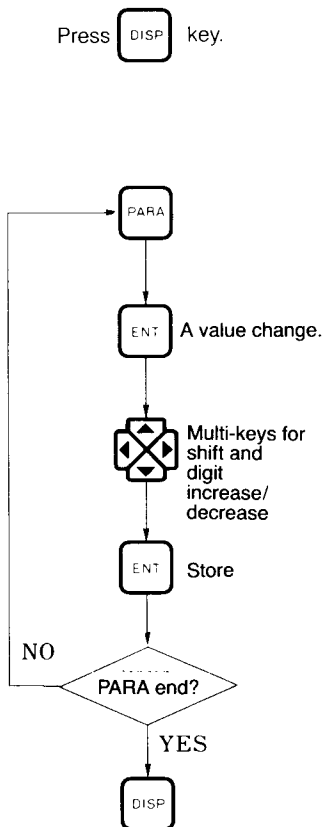
### SET UP Setup setting procedure



Step	Key operation	Display	Description of display	Remarks
1	Press  key.		Proceed to the next step, since the initial value is the preset value before delivery from factory.	See pages 18 and 20.
16	Press  key.	 	Program time unit is minute and second. ( : Minue and second)	
17	Press  key.	 	flashes.	
18	Press this key.	 	Digit 1 is displayed.	
19	Press  key.	 	1 is set.	
20	Press  key.	SP TM	SETUP has finished.	C30 to C33 are not related to setup.

## (3) Parameter setting example

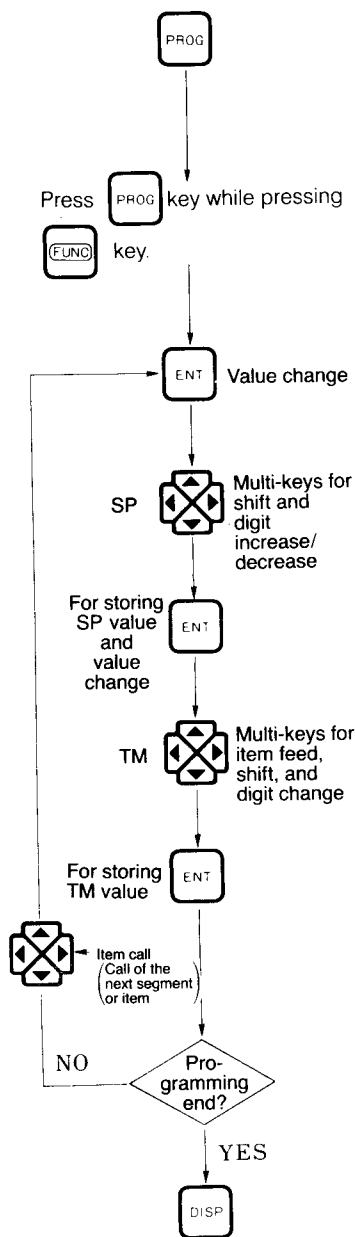
### PARAM Parameter setting procedure



Step	Key operation	Display	Description of displays	Remarks
1	Press  key.	 	Proceed t the next step, since the initial value is the preset value before delivery from factory.	See pages 24 and 25.
9	Press  key.	 	Change initial value  for setting DEV of event No.2.	
10	Press  key.	 	The last digit flashes.	
11	Press this key.	 	Change the digit to 2 .	Initial value 2 : Devi-ation
12	Press  key.	 	The higher side of the (+) DEV set point is on.	
13	Press  key.	 	Set the DEV event on-off range to 5°C in event No.2. There is no change because the initial value is 5 .	
14	Press  key.	SP TM	Parameters setting has finished.	

### (4) Programming example

#### Programming setting procedure



Step	Key operation	Display	Description of displays	Display of profile
1	Press  key.		A program No. is assigned. SP, TM LEDs light.	
2	Press  key while pressing  key.		Programming mode is set. PRG LED lights. decimal point lights.	
3	Press  key.		<b>Segment 1</b> The last digit of SP flashes. SP value setting (Temperature is set to °C.)	
4	Press this key first, and then, press this key.		After pressing shift (left) key, change the flashing digit by a digit increase key. Set SP=30 (°C).	
5	Press  key.		The last digit of TM flashes. TM value setting. (Time unit is set to minute/second.)	
6	Press this key first, and then, press this key.		Press shift: (left) key, and then, change the flashing digit by a digit increase key. Set TM=2.00 (min.)	
7	Press  key.		SP=30°C and TM=2 min have been stored.	
8	Press this key.		<b>Segment 2</b>	
9	Press  key.		SP value setting	
10	Repeat step 4.		SP=100(°C) is set.	
11	Press  key.		TM value setting	
12	Repeat step 6.		TM=4.00 (min) is set.	
13	Press  key.		SP=100°C and TM=4 min have been stored.	
	Press  key.		<b>Segment 9</b> PROG SEG: 1. 9. SP=30°C and TM=4 min have been stored.	

	Step	Key operation	Display	Description of displays	Display of profile
PV event	1	Press this key.		PRG LED lights continuously. PV EV1 LED lights.	
	2	Press this key.		Press an item feed (right) key continuously until  appears.	
	3	Press  key.		The last digit of PV value  flashes.	
	4	Press this key twice.		Shift	
	5	Press this key.		100 is displayed.	
	6	Press  key.		PV event 100°C is set.	
DEV event	7	Press this key.		DEV EV2 LED lights when  appears.	
	8	Press this key (four times)		Stop pressing the key when  appears.	
	9	Press  key.		The last digit  flashes.	
	10	Press this key.		5 is displayed.	
	11	Press  key.		DEV event 5°C is set.	
	12	Press this key.		is displayed.	
	13	Press  key.		The last digit  flashes.	
	14	Press this key first, and then, press this key.		600 is displayed.	
	15	Press  key.		DEV event 600°C is set.	

	Step	Key operation	Display	Description of display	Display of profile
Time event	16	Press this key.		T1 LED lights in <sup>SEG</sup> 7.	
	17	Press this key. (four times)		Stop pressing the key when <sup>SEG</sup> 2. appears.	
	18	Press  key.		The last digit  flashes.	
	19	Press this key first, and then, press this key.		0.00 is displayed.	
	20	Press  key.		T1 time event ON is set to 0 min.	
	21	Press this key first, and then, press this key.		37.00 is displayed.	
	22	Press  key.		T1 time event OFF is set to 37 min.	
	23	Repeat 16 to 21 steps. Press  key.		<sup>SEG</sup> 4. T2 LED T2 time event ON is set to 1 min. OFF is set to 7 min.	
	24	Repeat 16 to 21 steps. Press  key.		<sup>SEG</sup> 5. T3 LED T3 time event ON is set to 0 min. OFF is set to 7 min.	
	25	Repeat 16 to 21 steps. Press  key.		<sup>SEG</sup> 8. T4 LED T4 time event ON is set to 0 min. OFF is set to 4 min.	
PID	26	Press this key.		<sup>SEG</sup> 8. PID is displayed in 8. Since segments 1 to 4 apply to 1 group, go to segment 5.	
	27	Press this key.		<sup>SEG</sup> 5. is displayed.	
	28	Press  key.		PID 1 flashes.	
	29	Press this key.		No.2 PID group is set to segment 5.	
	30	Repeat 27 to 30 steps. Press  key.		No.2 PID group is applied to segment 5 to 6. No.3 PID group is applied to segments 7 to 9.	

	Step		Display		Display of profile
Guaranteed soak	31	Press this key.	g.S. no	3.5 (guaranteed soak) and no are displayed in <sup>SEG</sup> 9.	
	32	Press this key. (four times)	g.S. no	Display <sup>SEG</sup> 4.	
	33	Press  key.	g.S. <del>no</del>		
	34	Press this key.	g.S. <del>YES</del>		
	35	Press  key.	g.S. YES	Guaranteed soak is set in segment 4.	
PV event	36	Press this key.	P.S t A no	PV start YES or NO may be set in an optional segment.	
	37	Press  key.	P.S t A <del>no</del>		
	38	Press this key.	P.S t A <del>YES</del>		
	39	Press  key.	P.S t A YES	YES is set for PV start.	
Cycle	40	Press this key.	CYCL 0	Since no cycle is required, 0 is set.	
	41	Press  key.	 	Programming ends. After verifying with  keys again, press  key.	



# WORKSHEET FOR DCP211 SETUP, PARAMETER AND PID VALUE SETTING

Client

Model No.

Equipment Name :	Product Name :

D	C	P	2	1	1						
Tag Name											

Application Engineer	
Salesman	
Date	

## 1. Setup

No.	Indication, set point value at the delivery time from factory	Item	Client's set point
1	<input type="text" value="E 1"/> <input type="text" value="0"/>	Key lock 0 : No key lock 1 : SETUP change is not allowable. 2 : Setting data are not changeable. 3 : DISP key only is changeable.	<input type="text" value="E 1"/> <input type="text" value="0"/>
2	<input type="text" value="E 2"/> <input type="text" value="0"/>	Temperature unit 0 : Centigrade (°C) 1 : Fahrenheit (°F) T/C and RTD inputs only are displayed.	<input type="text" value="E 2"/> <input type="text" value="0"/>
3	<input type="text" value="E 3"/> <input type="text" value="0"/>	Control action 0 : Reverse action 1 : Direct action	<input type="text" value="E 3"/> <input type="text" value="0"/>
4	<input type="text" value="E 4"/> <input type="text" value="0"/>	MV at PV overrange 0 : Not provided 1 : Provided	<input type="text" value="E 4"/> <input type="text" value="0"/>
5	<input type="text" value="E 5"/> <input type="text" value="0.0"/>	Setting value at PV overrange 0.0 to 100.0% (Time proportional type) -10.0 to +110.0% (Current output type) Displayed only when 1 in C4.	<input type="text" value="E 5"/> <input type="text" value="0.0"/>
6	<input type="text" value="E 6"/> <input type="text" value="0"/>	0 to 12 (T/C) 20 to 35 (RTD) 40 to 45 (Linear)	<input type="text" value="E 6"/> <input type="text" value="0"/>
7	<input type="text" value="E 7"/> <input type="text" value="0"/>	Linear PV decimal point position 0 = <input type="text" value=""/> <input type="text" value=""/> <input type="text" value=""/> <input type="text" value=""/> 1 = <input type="text" value="."/> <input type="text" value=""/> <input type="text" value=""/> <input type="text" value=""/> 2 = <input type="text" value="."/> <input type="text" value="."/> <input type="text" value=""/> <input type="text" value=""/> 3 = <input type="text" value="."/> <input type="text" value="."/> <input type="text" value="."/> <input type="text" value=""/> Linear type only displayed.	<input type="text" value="E 7"/> <input type="text" value="0"/>
8	<input type="text" value="E 8"/> <input type="text" value="0"/>	Linear PV lower-limit -1999 to upper-limit U Linear type only is displayed.	<input type="text" value="E 8"/> <input type="text" value="0"/>
9	<input type="text" value="E 9"/> <input type="text" value="1000"/>	Linear PV upper-limit Lower-limit to 9999U Linear type only is displayed.	<input type="text" value="E 9"/> <input type="text" value="1000"/>
10	<input type="text" value="E 10"/> <input type="text" value="0"/>	SP limit lower-limit 0% to upper-limit of range	<input type="text" value="E 10"/> <input type="text" value="0"/>
11	<input type="text" value="E 11"/> <input type="text" value="100"/>	SP limit upper-limit Lower-limit to 100% of range	<input type="text" value="E 11"/> <input type="text" value="100"/>

No.	Indication, set point value at the delivery time from factory	Item	Client's set point
12	<input type="text" value="E 12"/> <input type="text" value="0"/>	Type of main output 0 : MV 1 : SP Current output type only is displayed.	<input type="text" value="E 12"/> <input type="text" value="0"/>
13	<input type="text" value="E 13"/> <input type="text" value="0"/>	Setting of SP4mA -1999 to +9999U Displayed only when 1 in C12. Current output type only is displayed.	<input type="text" value="E 13"/> <input type="text" value="0"/>
14	<input type="text" value="E 14"/> <input type="text" value="100"/>	Setting of SP20mA -1999 to +9999U Displayed only when 1 in C12. Current output type only is displayed.	<input type="text" value="E 14"/> <input type="text" value="100"/>
15	<input type="text" value="E 15"/> <input type="text" value="0"/>	Type of auxiliary output 0 : PV 1 : SP Displayed only when auxiliary output is provided.	<input type="text" value="E 15"/> <input type="text" value="0"/>
16	<input type="text" value="E 16"/> <input type="text" value="0"/>	Setting of auxiliary output 4mA -1999 to +9999U Displayed only when auxiliary output is provided.	<input type="text" value="E 16"/> <input type="text" value="0"/>
17	<input type="text" value="E 17"/> <input type="text" value="100"/>	Setting of auxiliary output 20mA -1999 to +9999U Displayed only when auxiliary output is provided.	<input type="text" value="E 17"/> <input type="text" value="100"/>
18	<input type="text" value="E 18"/> <input type="text" value="0"/>	Display at programming of EV1.2 0 : Displayed 1 : Not displayed	<input type="text" value="E 18"/> <input type="text" value="0"/>
19	<input type="text" value="E 19"/> <input type="text" value="0"/>	Display at programming of T1 to T4 0 : Displayed 1 : Not displayed	<input type="text" value="E 19"/> <input type="text" value="0"/>
20	<input type="text" value="E 20"/> <input type="text" value="0"/>	Display at programming of PID G.SOAK 0 : Provided 1 : Not provided	<input type="text" value="E 20"/> <input type="text" value="0"/>
21	<input type="text" value="E 21"/> <input type="text" value="0"/>	Display at programming of PV start, cycle, and pattern link. 0 : Not provided 1 : Provided	<input type="text" value="E 21"/> <input type="text" value="0"/>
22	<input type="text" value="E 22"/> <input type="text" value="0"/>	Communication address 0, 1 to 254 Displayed only when communication is provided.	<input type="text" value="E 22"/> <input type="text" value="0"/>
23	<input type="text" value="E 23"/> <input type="text" value="0"/>	Communication speed 0 : 9600 (BPS) 1 : 4800 2 : 2400 3 : 1200 Displayed only when communication is provided.	<input type="text" value="E 23"/> <input type="text" value="0"/>

No.	Indication, set point value at the delivery time from factory	Item	Client's set point	No.	Indication, set point value at the delivery time from factory	Item	Client's set point
24	C 2 4 0	Communication code 0 : 8 bits, even parity bit, 1 stop bit 1 : 8 bits, not parity bit, 2 stop bits Displayed only when communication is provided.	C 2 4	28	C 2 8 0	Alarm display 0 : Displayed 1 : Not displayed	C 2 8
26	C 2 6 0	PV display 1 : Displayed 2 : Not displayed 3 : Not displayed when fixed at 0% of range.	C 2 6	29	C 2 9 0	Time unit of program 0 : min/hr 1 : sec/min	C 2 9
27	C 2 7 0	Time display 0 : Segment remaining time 1 : Operation progress time	C 2 7				

## 2. Parameter

No.	Indication, set point value at the delivery time from factory	Item	Client's set point	No.	Indication, set point value at the delivery time from factory	Item	Client's set point
1	P r t c 0	Program protect 0 : Protected 1 : Not protected	P r t c	8	d i f f 5	ON/OFF control differential 0 to 100U Displayed only in 0D, and 6D types.	d i f f
2	F i l t 0.0	PV filter constant 0.0 to 120.0 sec.	F i l t	9	E t 1 0	Selection of event 1 0 : PV (Direct) 1 : PV (Reverse) 2 : Deviation (Direct) 3 : Deviation (Reverse) 4 : RUN 5 : READY 6 : END	E t 1
3	P b i a 0	PV bias -100 to +100U	P b i a	10	H y s 1 5	Event 1 hysteresis 0 to 100U	H y s 1
4	S b i a 0	SP bias -50 to +50% FS	S b i a	11	E t 2 0	Selection of event 2 0 : PV (Direct) 1 : PV (Reverse) 2 : Deviation (Direct) 3 : Deviation (Reverse) 4 : RUN 5 : READY 6 : END	E t 2
5	G . S . o a k 5	G.SOAK 0 to 100U	G . S . o a k	12	H y s 2 5	Event 2 hysteresis 0 to 100U	H y s 2
6	c y 1 0	Time proportional output cycle 5 to 120 sec. (Relay type) 1 to 60 sec. (Voltage type) 0D and 6D types only are displayed.	c y	13	r P i d 0	PID operation initialize at advance 0 : PID operation is not initialized. 1 : PID operation is initialized.	r P i d
7	o u t l 1 0 0 . 0	Manipulated variable change limit 0.0 to 100.0 (Every 0.5 sec.)	o u t l				



### 3. PID constant setting

No.	Indication, set point value at the delivery time from factory	Item	Client's set point
1	<div style="border: 1px solid black; padding: 2px; display: inline-block;">R t</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0</div>	0 : AT is not executed 1 : Method 1 is executed by ATkey. 2 : Method 2 is executed by ATkey.  Displayed only when auto tuning is provided.	<div style="border: 1px solid black; padding: 2px; display: inline-block;">R t</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
2	<div style="border: 1px solid black; padding: 2px; display: inline-block;">P - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 0 0 . 0</div>	Proportional band 1 0.0 to 999.9% (Time proportional) 0.1 to 999.9% (Current output)	<div style="border: 1px solid black; padding: 2px; display: inline-block;">P - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
3	<div style="border: 1px solid black; padding: 2px; display: inline-block;">I - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0</div>	Integral time 1 0 to 3600 sec. Displayed when P - 1 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">I - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
4	<div style="border: 1px solid black; padding: 2px; display: inline-block;">d - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0</div>	Derivative time 1 0 to 1200 sec. Displayed when P - 1 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">d - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
5	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o L - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0 . 0</div> or <div style="border: 1px solid black; padding: 2px; display: inline-block;">- 1 0 . 0</div>	Manipulated variable lower-limit 1 0.0 to upper-limit % (Time proportional) -10.0 to upper-limit % (Current output) Displayed when P - 1 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o L - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
6	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o H - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 0 0 . 0</div> or <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 1 0 . 0</div>	Manipulated variable upper-limit 1 Lower-limit to 100.0% (Time proportional) Lower-limit to 110.0% (Current output) Outputted when P - 1 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o H - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
7	<div style="border: 1px solid black; padding: 2px; display: inline-block;">r E - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">5 0 . 0</div>	Manual reset 1 0.0 to 100.0% Displayed when P - 1 ≠ 0 and I ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">r E - 1</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
8	<div style="border: 1px solid black; padding: 2px; display: inline-block;">P - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 0 0 . 0</div>	Proportional band 2 0.0 to 999.9% (Time proportional) 0.1 to 999.9% (Current output)	<div style="border: 1px solid black; padding: 2px; display: inline-block;">P - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
9	<div style="border: 1px solid black; padding: 2px; display: inline-block;">I - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0</div>	Integral time 2 0 to 3600 sec. Displayed when P - 2 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">I - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
10	<div style="border: 1px solid black; padding: 2px; display: inline-block;">d - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0</div>	Derivative time 2 0 to 1200 sec. Displayed when P - 2 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">d - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
11	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o L - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0 . 0</div>	Manipulated variable lower-limit 2 0.0 to upper-limit % (Time proportional) -10.0 to upper-limit % (Current output) Displayed when P - 2 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o L - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>

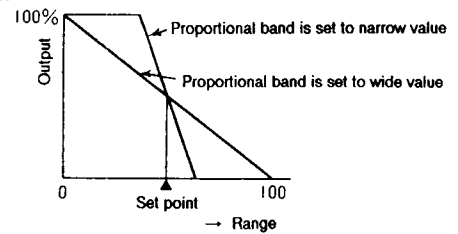
No.	Indication set point value at the delivery time from factory	Item	Client's set point
12	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o H - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 0 0 . 0</div> or <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 1 0 . 0</div>	Manipulated variable lower-limit 2 Lower-limit to 100.0% (Time proportional) Lower-limit to 110.0% (Current output) Displayed when P - 2 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o H - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
13	<div style="border: 1px solid black; padding: 2px; display: inline-block;">r E - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">5 0 . 0</div>	Manual reset 2 0.0 to 100.0% Displayed when P - 2 ≠ 0 and I ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">r E - 2</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
14	<div style="border: 1px solid black; padding: 2px; display: inline-block;">P - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 0 0 . 0</div>	Proportional band 3 0.0 to 999.9% (Time proportional) 0.1 to 999.9% (Current output)	<div style="border: 1px solid black; padding: 2px; display: inline-block;">P - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
15	<div style="border: 1px solid black; padding: 2px; display: inline-block;">I - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0</div>	Integral time 3 0 to 3600 sec. Displayed when P - 3 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">I - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
16	<div style="border: 1px solid black; padding: 2px; display: inline-block;">d - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0</div>	Derivative time 3 0 to 1200 sec. Displayed when P - 3 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">d - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
17	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o L - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0 . 0</div> or <div style="border: 1px solid black; padding: 2px; display: inline-block;">- 1 0 . 0</div>	Manipulated variable lower-limit 3 0.0 to upper-limit (Time proportional) -10.0 to upper-limit (Current output) Outputted when P - 3 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o L - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
18	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o H - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 0 0 . 0</div> or <div style="border: 1px solid black; padding: 2px; display: inline-block;">1 1 0 . 0</div>	Manipulated variable upper-limit 3 Lower-limit to 100.0 (Time proportional) Lower-limit to 110.0 (Current output) Displayed when P - 3 ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">o H - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
19	<div style="border: 1px solid black; padding: 2px; display: inline-block;">r E - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">5 0 . 0</div>	Manual reset 3 0.0 to 100.0% Displayed when P - 3 ≠ 0 and I ≠ 0	<div style="border: 1px solid black; padding: 2px; display: inline-block;">r E - 3</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>
20	<div style="border: 1px solid black; padding: 2px; display: inline-block;">I o u t</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;">0 . 0</div>	PID operation Initial MV 0.0 to 100.0% Displayed, if at least one P=0 out of 1 to 3 groups.	<div style="border: 1px solid black; padding: 2px; display: inline-block;">I o u t</div> <div style="border: 1px solid black; padding: 2px; display: inline-block;"></div>

## General PID Actions

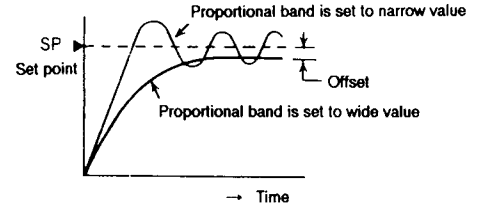
### 1. Proportional band P

- (1) When the proportional band is wide, an overshoot is difficult to occur on arrival at the set point, but an offset from the set point is produced. When the proportional band is narrow on the contrary, an overshoot occurs and the control amplitude is waved as in on-off action.
  - The offset is reduced.
  - When the proportional band is minimized, the maximum and minimum control outputs are repeated, and the output amplitude is maximized. The offset is also minimized.
- (2) When the proportional band is narrowed, the following effect appear.
  - The offset is reduced.
  - When the proportional band is minimized, the maximum and minimum control outputs are repeated, and the output amplitude is maximized. The offset is also minimized.
- (3) In electric furnaces, the proportional band may be generally set to narrower than about 10%.

#### P control action



#### P control effect



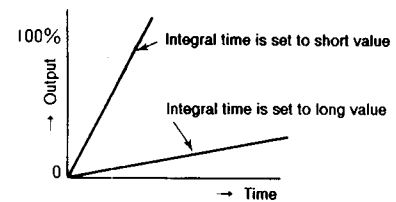
### 2. Integral I

- (1) The integral time functions in such a direction that the offset caused by the proportional control is eliminated as the time elapses.
 

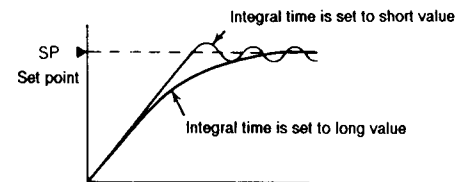
If the integral time is shortened to eliminate the offset in a short time, the derivative action is intensified and the control is disturbed on the contrary, thus causing a hunting.

Therefore, change over the integral time from a long value to a short value, and find an optimum control constant.
- (2) As the integral value is shortened, the following effects appear.
  - The offset is reduced more speedily.
  - The control output amplitude is increased, thus causing a hunting.
- (3) In electric furnaces, the integral time may be generally set to shorter than about 150 sec.

#### I control action



#### I control effect



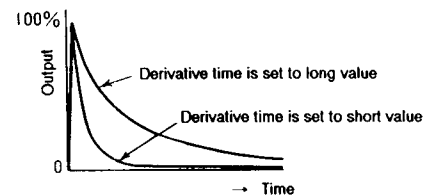
### 3. Derivative D

- (1) The derivative time functions to output a large manipulated variable against a sudden disturbance, and thereby restore the control to the original.
 

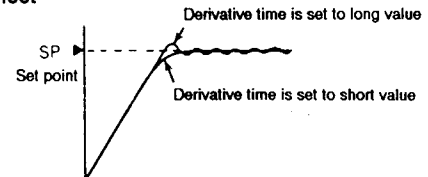
When the derivative time is made long, the large manipulated variable is activated for a long time, and therefore the control is caused to be disturbed on the contrary.

Therefore, change over the setting of the derivative time a short value to a long value, and find an optimum control constant.
- (2) As the derivative time becomes longer, the following effects appear.
  - Both the control output amplitude and time become smaller little by little.
  - The derivative time adjustment has no effect on the offset correction.
- (3) In electric furnaces, the derivative time may be generally set to longer than about 30 sec.
- (4) A optimum derivative value is generally about 1/4 of the integral value.

#### D control action



#### D control effect



*Specifications are subject to change without notice.*

**YAMATAKE**

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